



**WPI**



# Multi-Objective Reinforcement Learning for Cognitive Radio-based Satellite Communications

Paulo Ferreira, Randy Paffenroth, Alexander Wyglinski - (*WPI*)

Timothy Hackett, Sven Bilen - (*Penn State*)

Richard Reinhart, Dale Mortensen - (*NASA GRC*)

NASA GRC Grant: "Intelligent Media Access Protocol for SDR-based Satellite Communications."

Grant number: NNC14AA01A

# Agenda

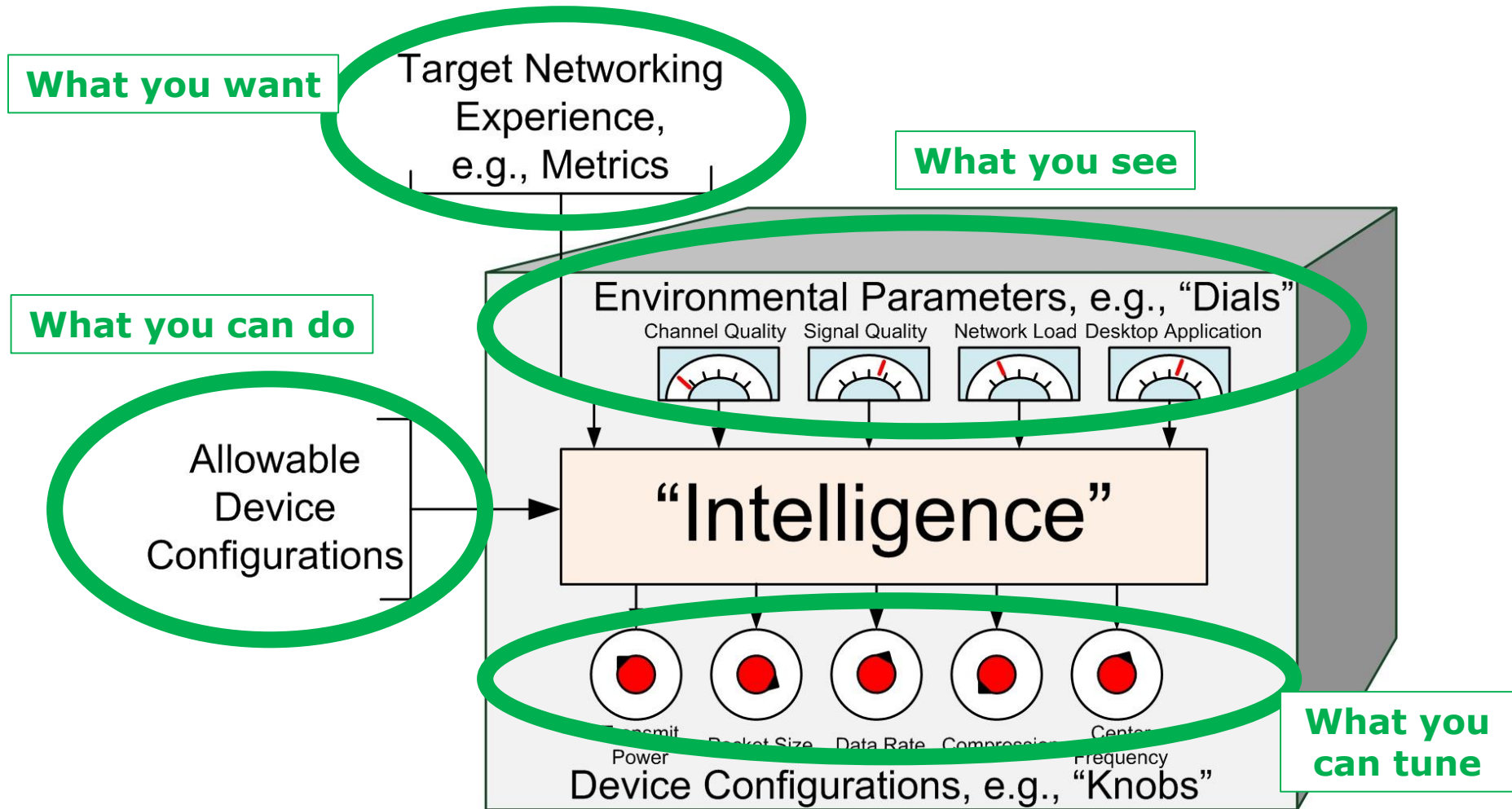
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- What is a Cognitive Radio?
- CR applications
- The problem: Multi-objective performance
- Reinforcement Learning: The solution
- Satcom RL performance

# What is a Cognitive Radio ?



# What is a Cognitive Radio ?

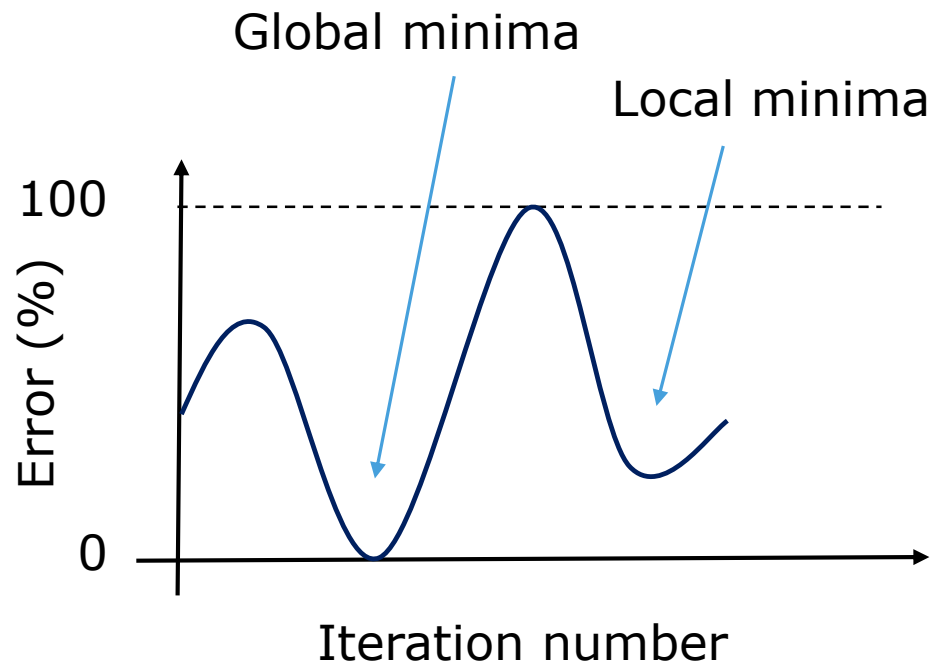


T. Collins, A.M. Wyglinski. "Enabling Security in Cognitive Radios and Wireless Spectrum." MILCOM Tutorial, 2014.

# What is a Cognitive Radio ?

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- Learning algorithm
  - Explore vs. Exploit



# CR applications



# CR applications

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- **Satcom**



Reinhart, R. C. Using International Space Station For Cognitive System Research And Technology With Space-based Reconfigurable Software Defined Radios. 66<sup>th</sup> International Astronautical Congress, IAC 2015.

# CR Satcom – What you tune: PHY layer

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- Modulation scheme
- Encoding scheme
- Symbol rate
- Bandwidth
- Carrier frequency
- ADC/DAC resolution
- Antenna
- Transmission power level



# Multi-Objective Comms Performance

The problem



# Multi-objective comms performance

Table 1. Radio parameter adaptation inter-relationship

Adaptation	Goals	Consequences	Conflicts	Constants
$\downarrow M$	$\min(\text{BER}), \min(P)$	$\downarrow R, P, \text{BER}$	$\max(R)$	$E_b$
$\uparrow M$	$\max(R)$	$\uparrow R, P, \text{BER}$	$\min(\text{BER}), \min(P)$	$E_b$
$\uparrow R$	$\max(R), W \text{ const.}^*$	$\uparrow W, P$	$\min(P), W \text{ const.}^*$	$M, E_b$
$\downarrow R$	$\min(P), W \text{ const.}^*$	$\downarrow W, P$	$\max(R), W \text{ const.}^*$	$M, E_b$

\* Keeping  $W$  constant can be a goal or a conflicting goal while adapting  $R$ .

M – modulation and encoding schemes

R – data rate

BER – bit error rate

P – transmission power

W – bandwidth

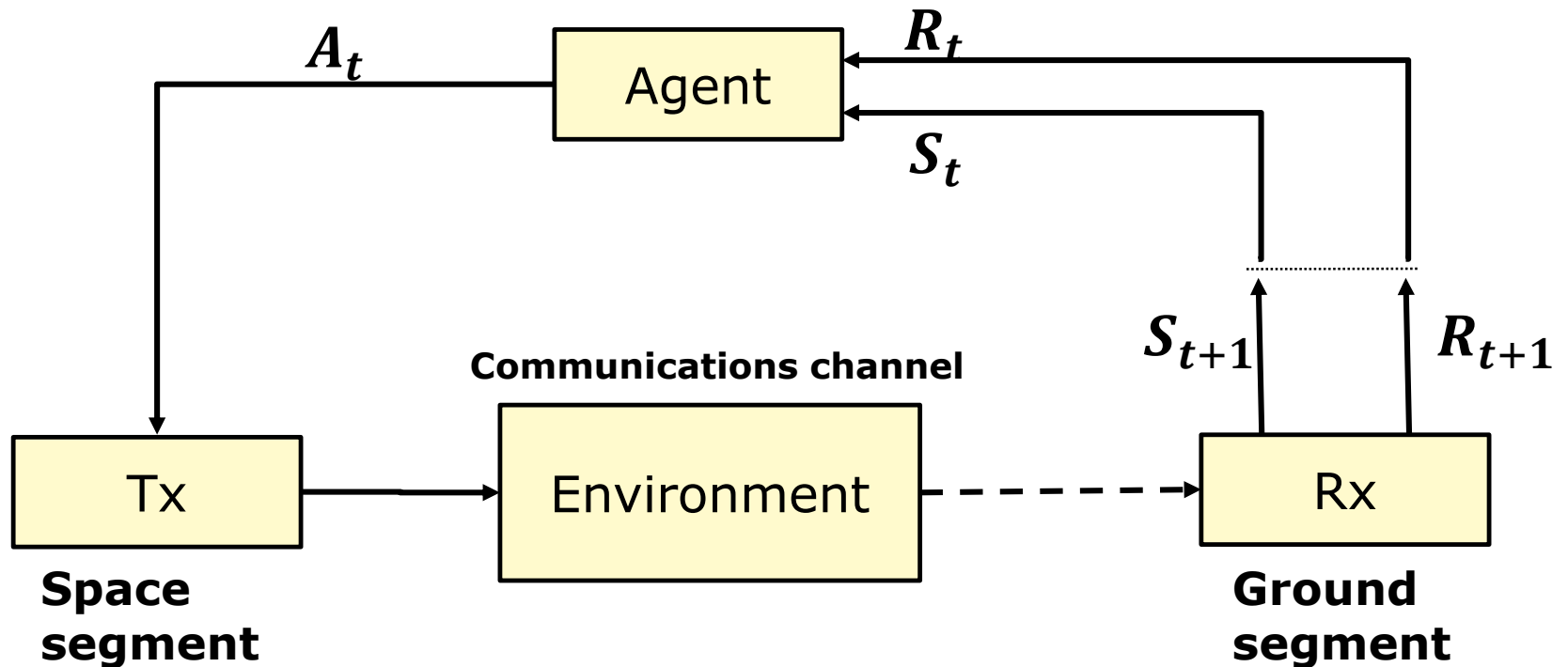
$E_b$  – energy per bit

# Reinforcement Learning

The solution

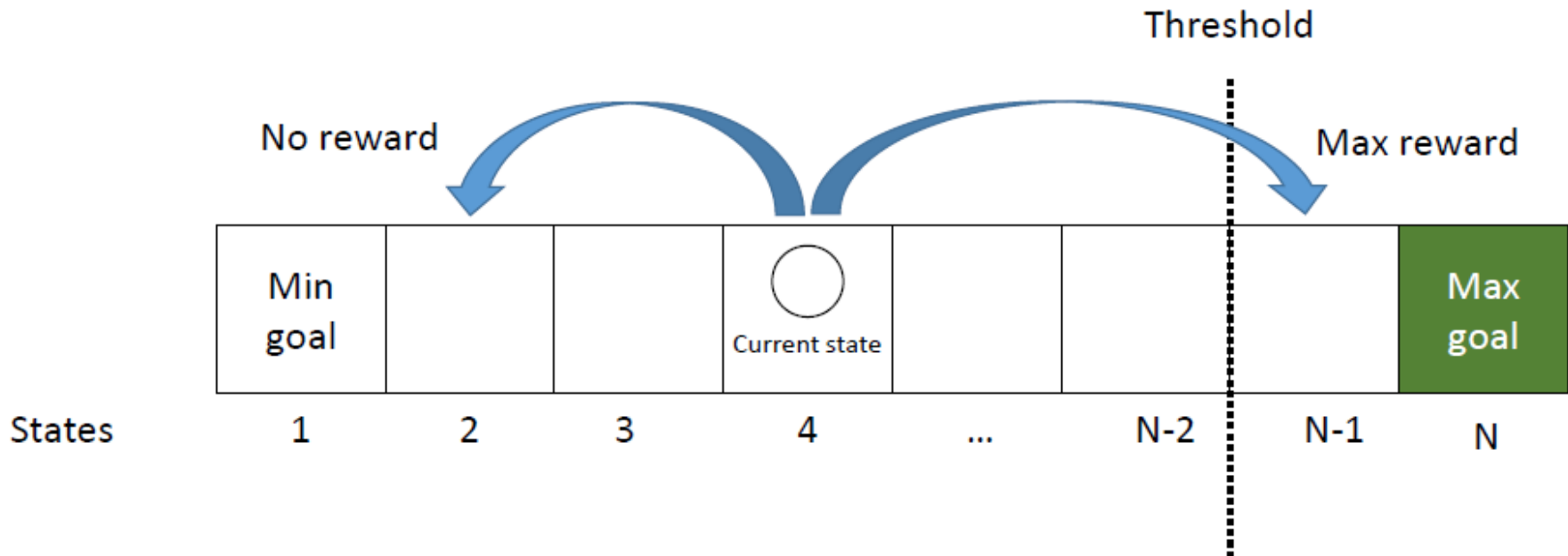


# Reinforcement Learning



$A_t$  = action  
 $R_t$  = reward  
 $S_t$  = state

# Reinforcement Learning



# Reinforcement Learning

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- Satcom  $Q(S, A)$

$$Q_{k+1}(s_k, u_k) = Q_k(s_k, u_k) + \alpha_k r_{k+1}$$

$u_k = h(s_k)$   $\longrightarrow$  State-action policy

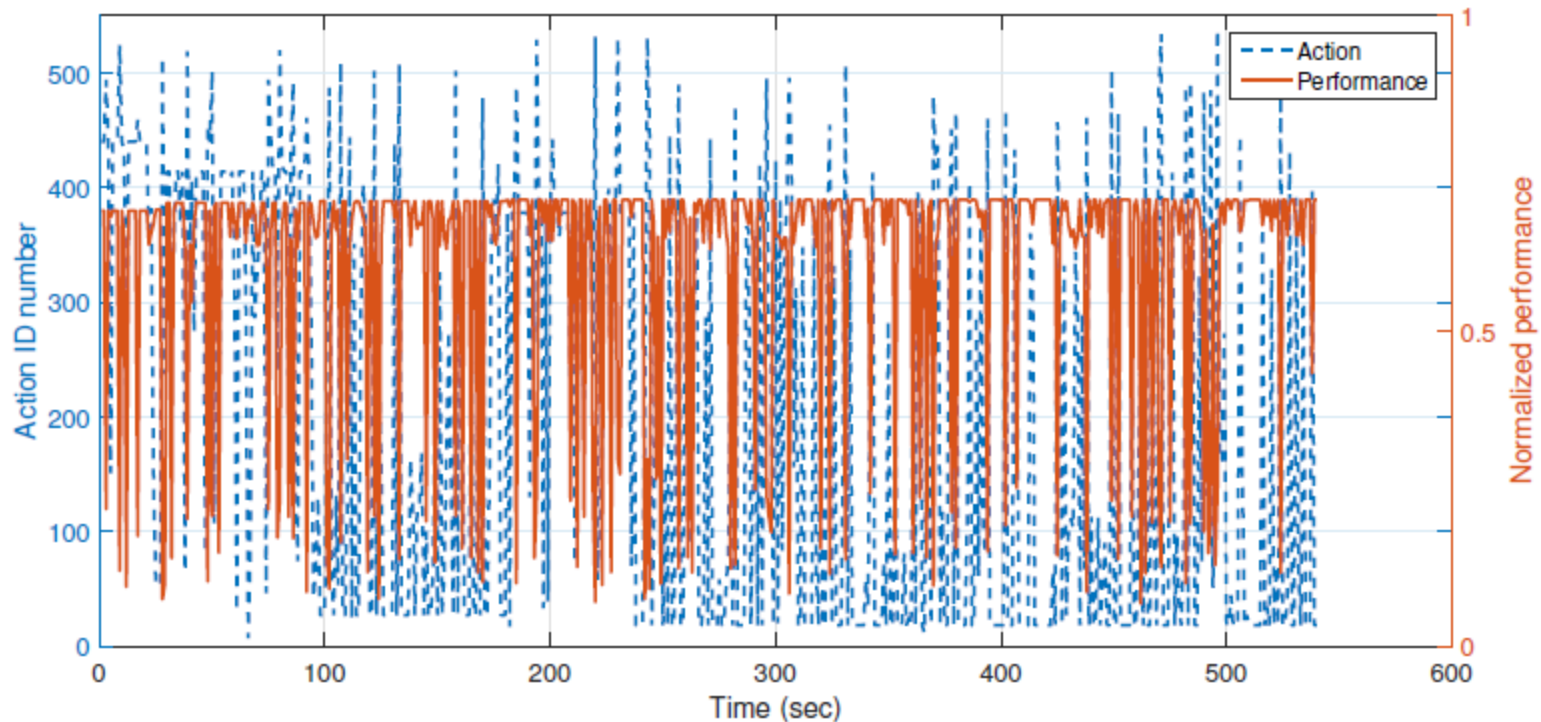
$s_{k+1} = g(s_k, u_k)$   $\longrightarrow$  State-transition function

$r_{k+1} = \rho(s_k, u_k)$   $\longrightarrow$  Reward function

# Satcom RL performance

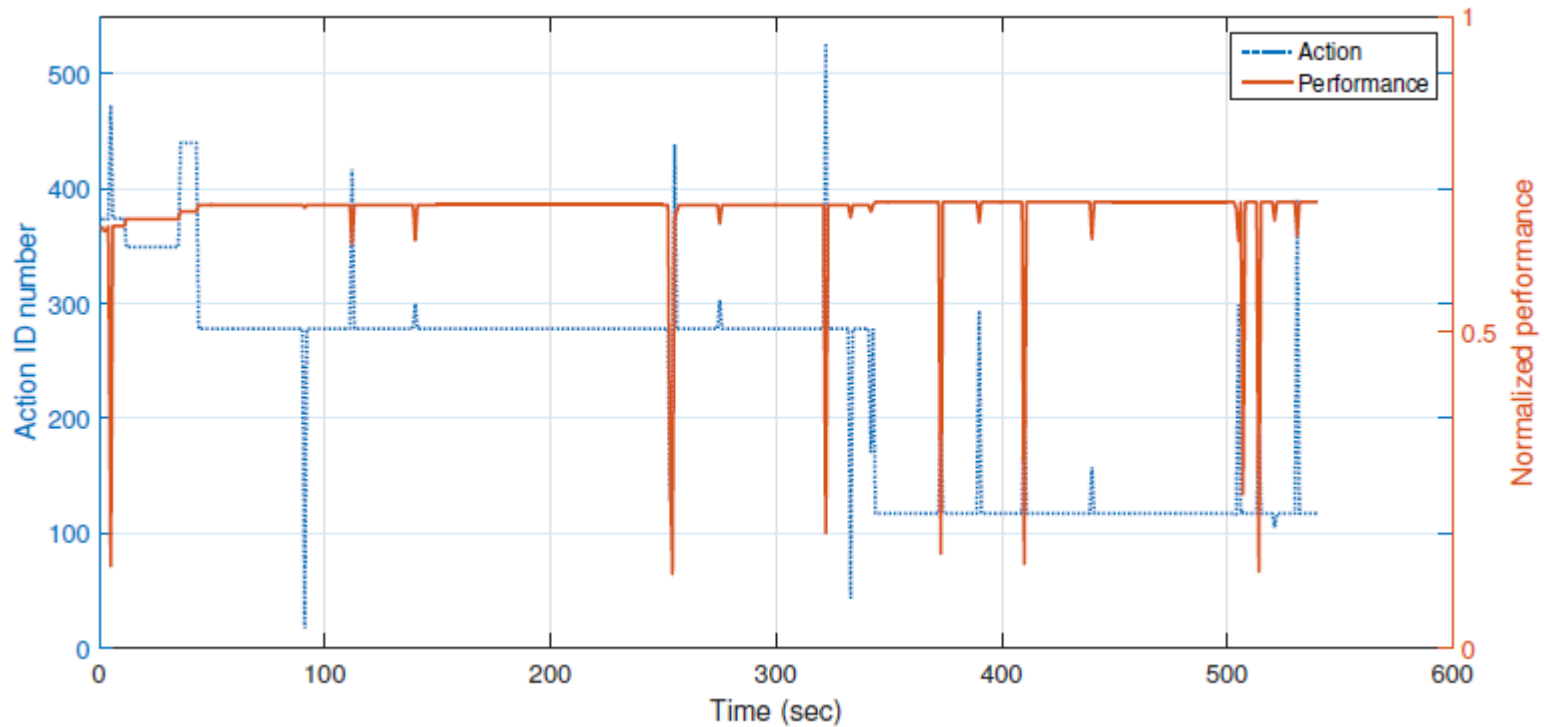


# Fixed exploration probability ( $\varepsilon = 0.5$ )

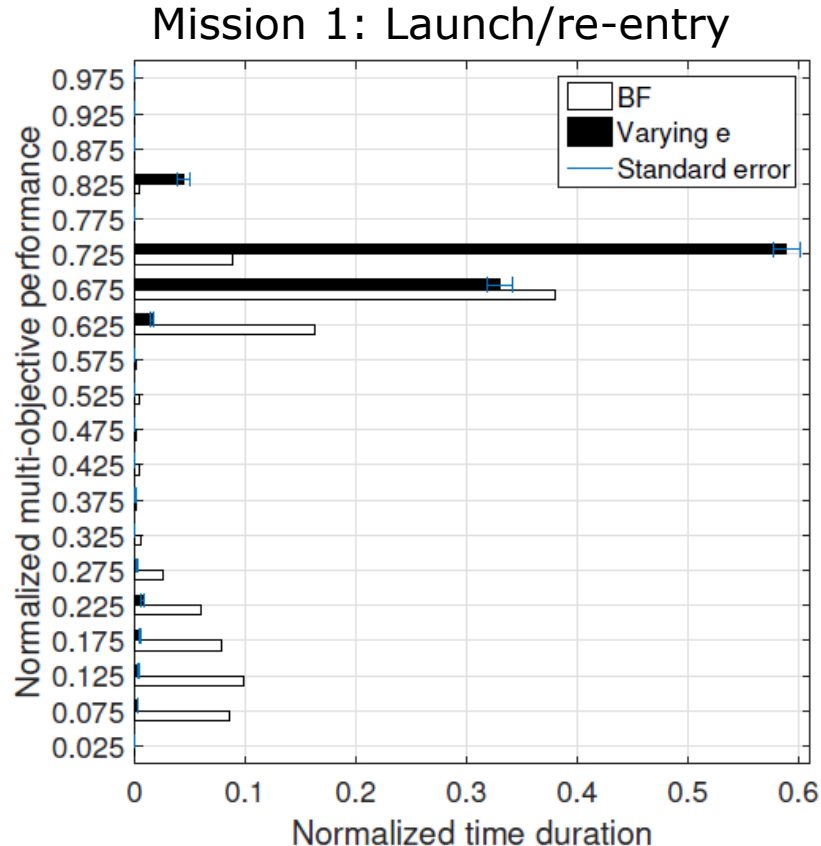




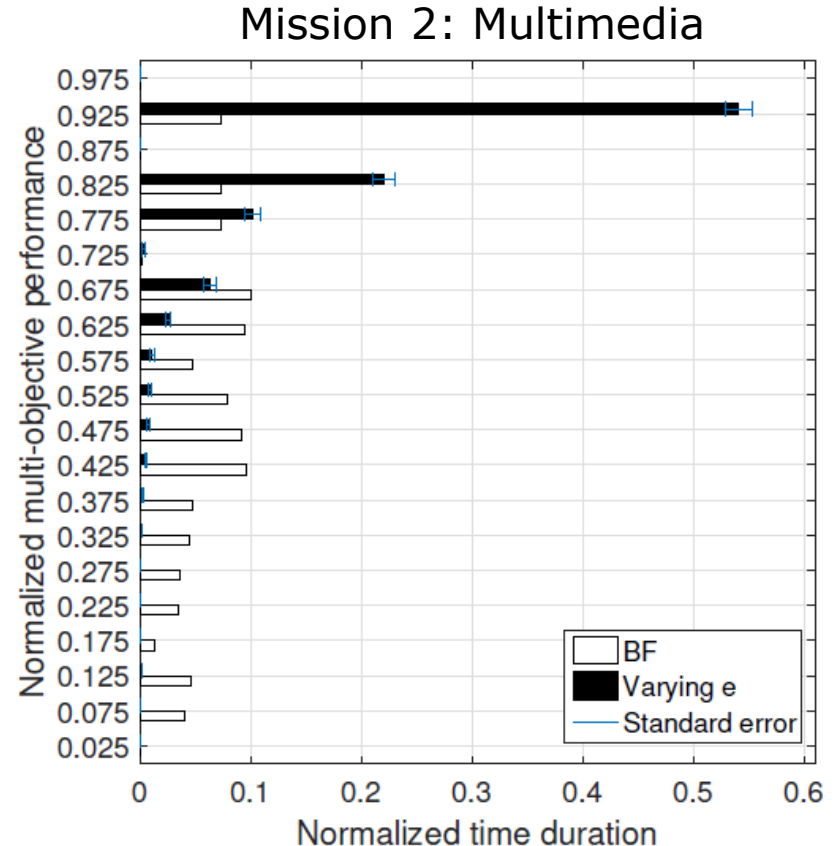
# Variable exploration probability $\varepsilon$



# Time spent at performance levels



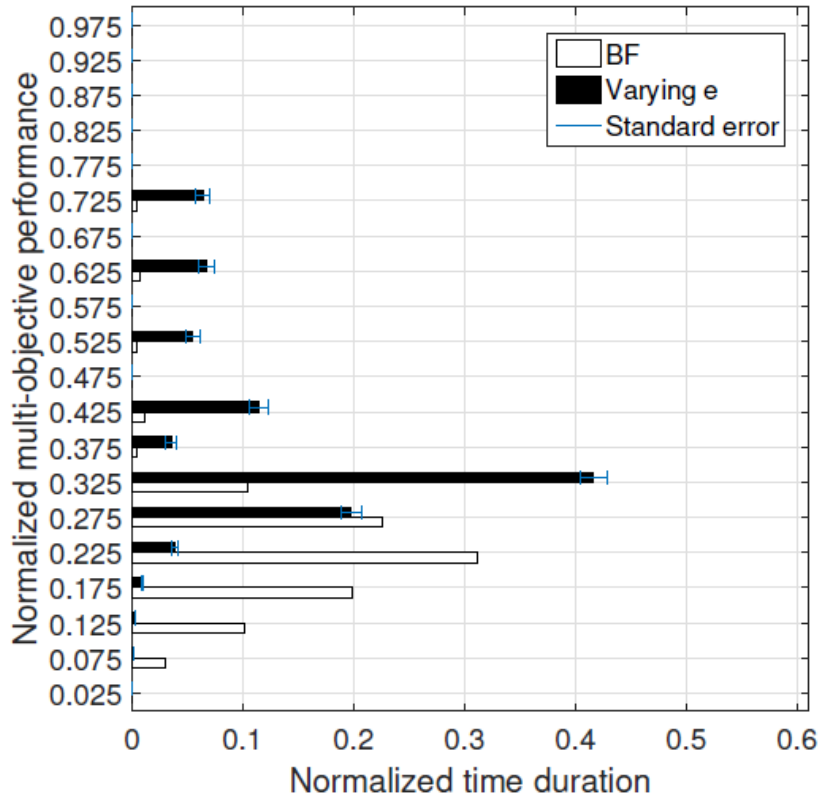
(a)



(b)

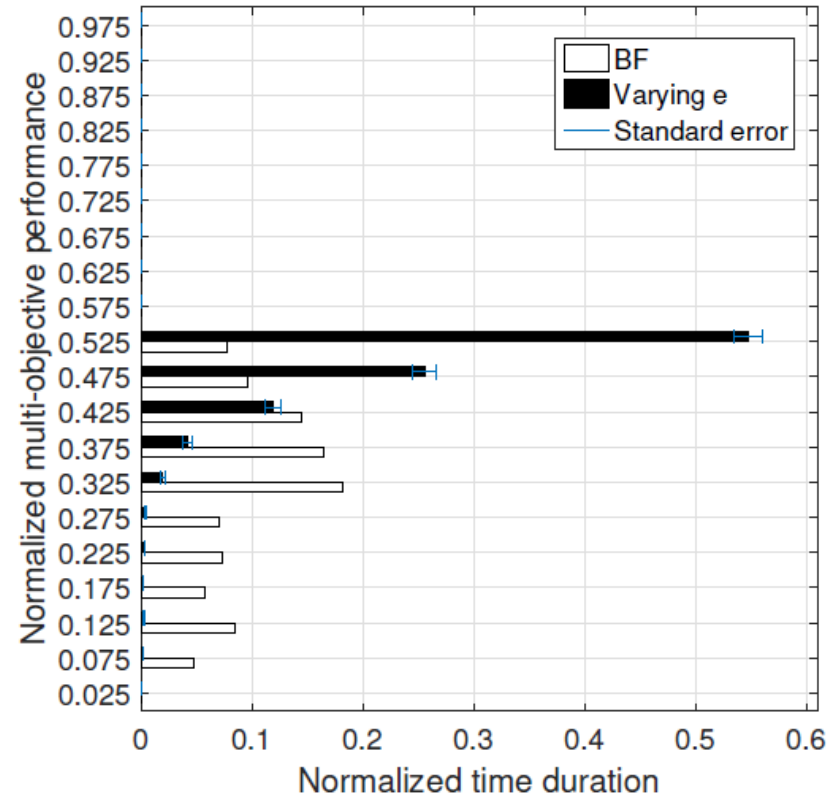
# Time spent at performance levels

Mission 3: Power saving



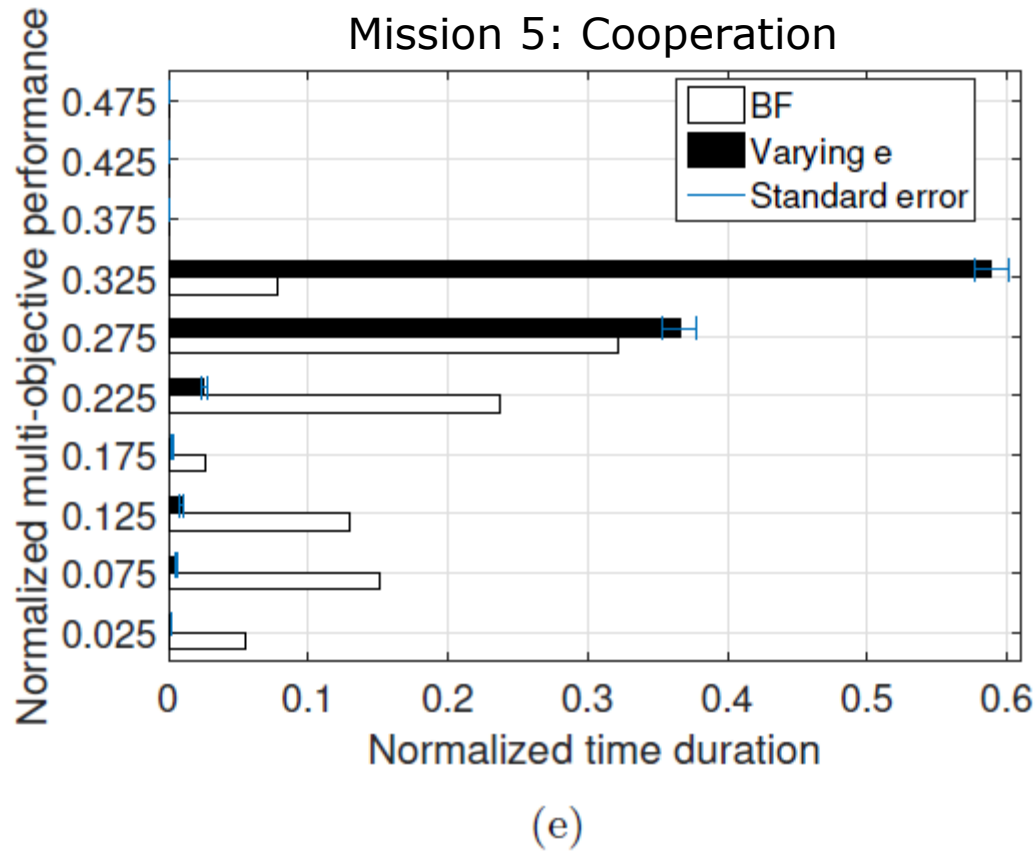
(c)

Mission 4: Normal



(d)

# Time spent at performance levels



# THANK YOU!



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# Contact us



**PRFERREIRA@wpi.edu**



**ALEXW@wpi.edu**

**<http://www.wireless.wpi.edu/>**